

Grass on HPC

What is Grass?

Geographic Resources Analysis Support System, commonly referred to as GRASS GIS, is a Geographic Information System (GIS) used for geospatial data management and analysis, image processing, graphics/maps production, spatial modeling, and visualization. GRASS is currently used in academic and commercial settings around the world, as well as by many governmental agencies and environmental consulting companies.

Links:

[Official Website](#)

[Documentation](#)

Versions Available:

The following versions are available on the cluster:

- Grass-v6.4.3

How to load Grass?

To load Grass, use the following commands:

```
#Load the Grass module  
module load physical/grass
```

To verify if the module and dependencies are loaded correctly, use the following command.

```
#See dependencies
module list
```

This should list all the software and dependencies that are loaded. In this case, only grass will be loaded. If user wants to create python environment compatible for grass, load the Miniconda3 module.

How to use Grass?

The main executable of the program is **grass64**.

```
Usage:
  grass64 [-h | -help | --help] [-v | --version] [-c]
          [-text | -gui | -tcltk | -oldtcltk | -wxpython | -wx]
          [[ [<GISDBASE>/ ] <LOCATION_NAME>/ ] <MAPSET> ]

Flags:
  -h or -help or --help      print this help message
  -v or --version            show version information and exit
  -c                          create given mapset if it doesn't
exist
  -text                       use text based interface
                              and set as default
  -gui                        use graphical user interface
  (wxpython by default)
                              and set as default
  -tcltk                      use Tcl/Tk based graphical user
interface
                              and set as default
  -oldtcltk                  use old Tcl/Tk based graphical user
interface
                              and set as default
  -wxpython or -wx           use wxPython based graphical user
```

```

interface
                                and set as default

Parameters:
GISDBASE                        initial database (path to GIS data)
LOCATION_NAME                     initial location
MAPSET                           initial mapset

GISDBASE/LOCATION_NAME/MAPSET    fully qualified initial mapset
directory

Environment variables relevant for startup:
GRASS_GUI                       select GUI (text, gui, tcltk,
oldtcltk, wxpython)
GRASS_TCLSH                      set tclsh shell name to override
'tclsh'
GRASS_WISH                       set wish shell name to override
'wish'
GRASS_HTML_BROWSER              set html web browser for help pages
GRASS_ADDON_PATH                set additional path(s) to local GRASS
modules
GRASS_BATCH_JOB                 shell script to be processed as batch
job
GRASS_PYTHON                    set python shell name to override
'python'

```

See the following links for tutorial and HPC resources for using grass,

[QuickStart](#)

[HPC scripts](#)

Where to find help?

If you are stuck on some part or need help at any point, please contact OIT at the following address.

<https://ua-app01.ua.edu/researchComputingPortal/public/oitHelp>

